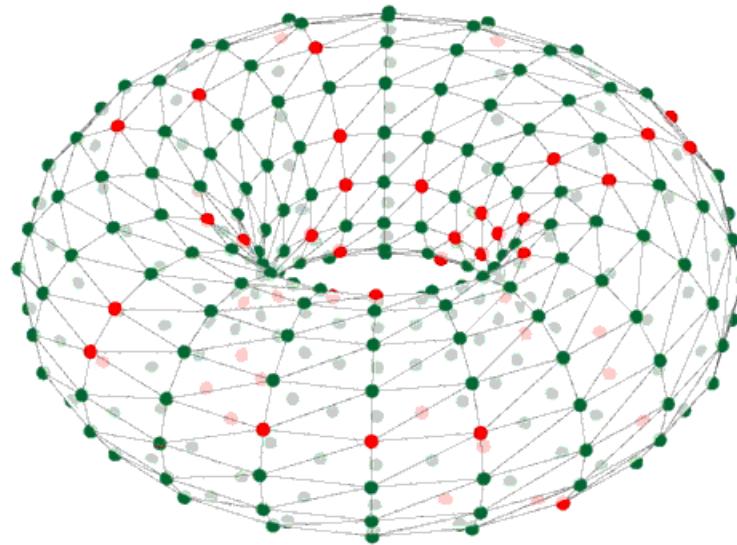


Synaptic plasticity on SpiNNaker with PyNN



Sergio Davies

SpiNNaker Workshop
September 2015



European Research Council
Established by the European Commission



Human Brain Project

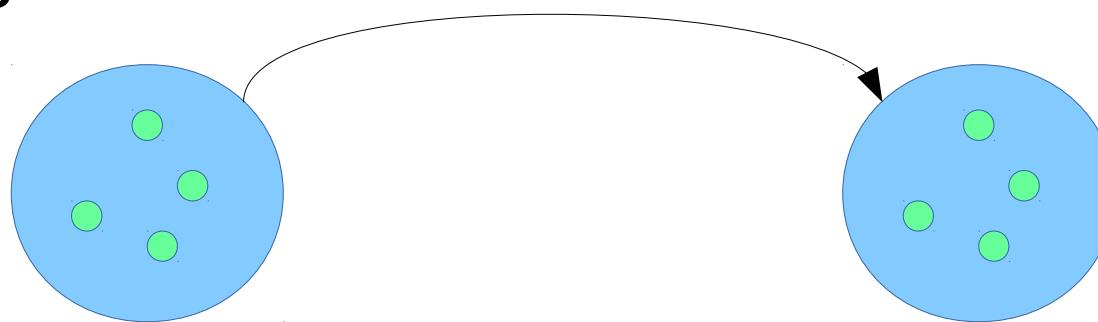


Neural network description

A neural network is usually described in terms of:

- Populations of neurons
- Projections between populations

Each population and projection has its own properties



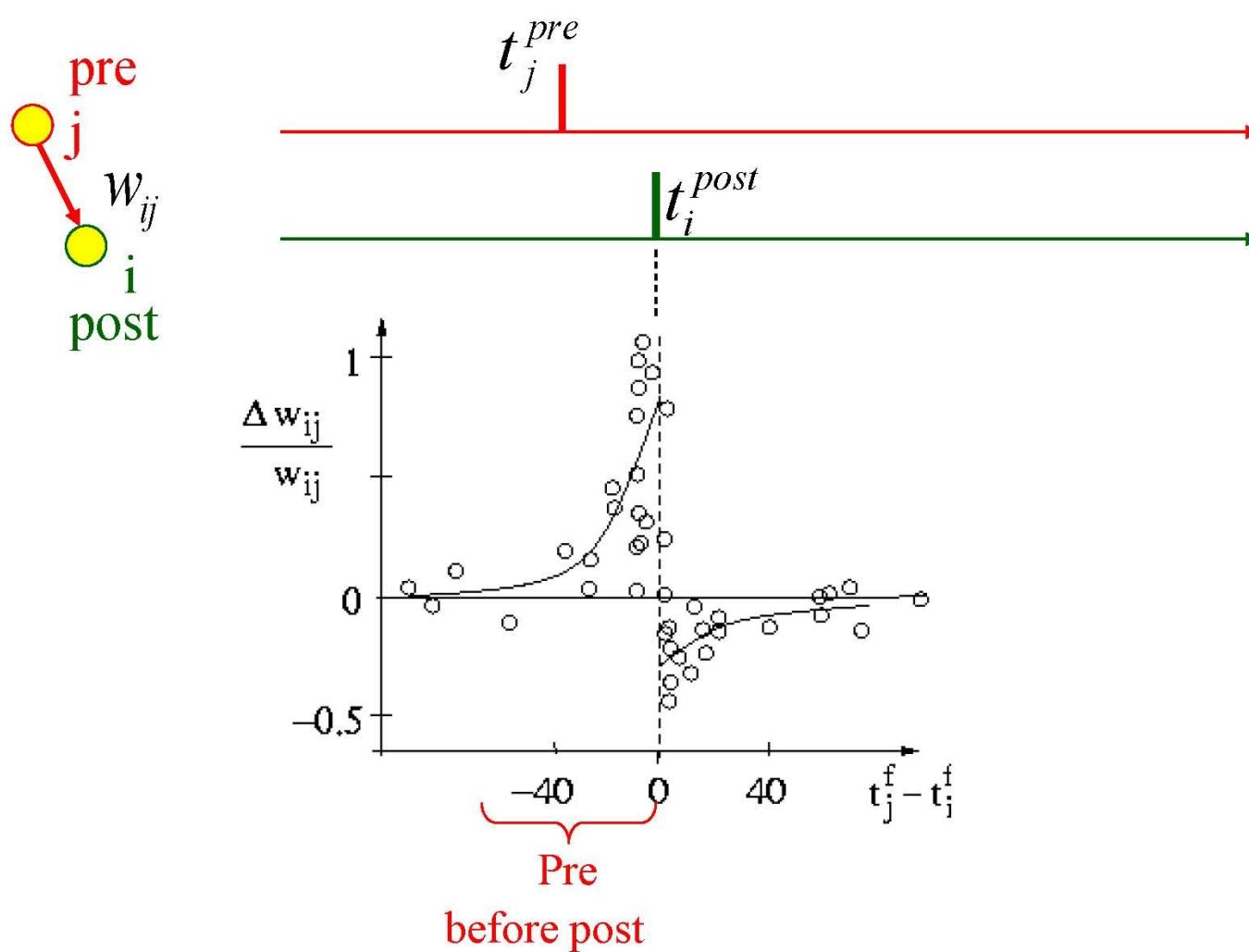
Projections

Attributes of the projections include (but are not limited to):

- Pre-synaptic population
- Post-synaptic population
- Connector type (All-To-All, One-To-One, etc.)
- Target – Synapse type (Excitatory, Inhibitory)
- Static or **Dynamic attributes**

Plasticity rules (1/2)

STDP spike pair rule



Plasticity rules (2/2)

Other rules available on SpiNNaker in “sPyNNakerExtraModelsPlugin” module:

- **Vogels** [*Vogels et al. (2011)*]
- **Triplet-based rule** [*J.-P. Pfister et al. (2006)*]
- **More...**

Behaviour dependence

Behaviour of plasticity rules may depend on one or more parameters:

- Weight dependence
- Time dependence

Weight dependence

- Additive weight dependence
- Multiplicative weight dependence

Weight Dependence example:

```
PyNN.AdditiveWeightDependence  
(w_min, w_max, A_plus, A_minus)
```

Timing dependence

- SpikePairRule
- Vogels2011Rule
- Etc.

Timing Dependence example:

```
PyNN.SpikePairRule  
(tau_plus, tau_minus, nearest)
```

Example

- Definition of a learning rule:

```
time_rule = SpikePairRule(tau_plus=1, tau_minus=1)
```

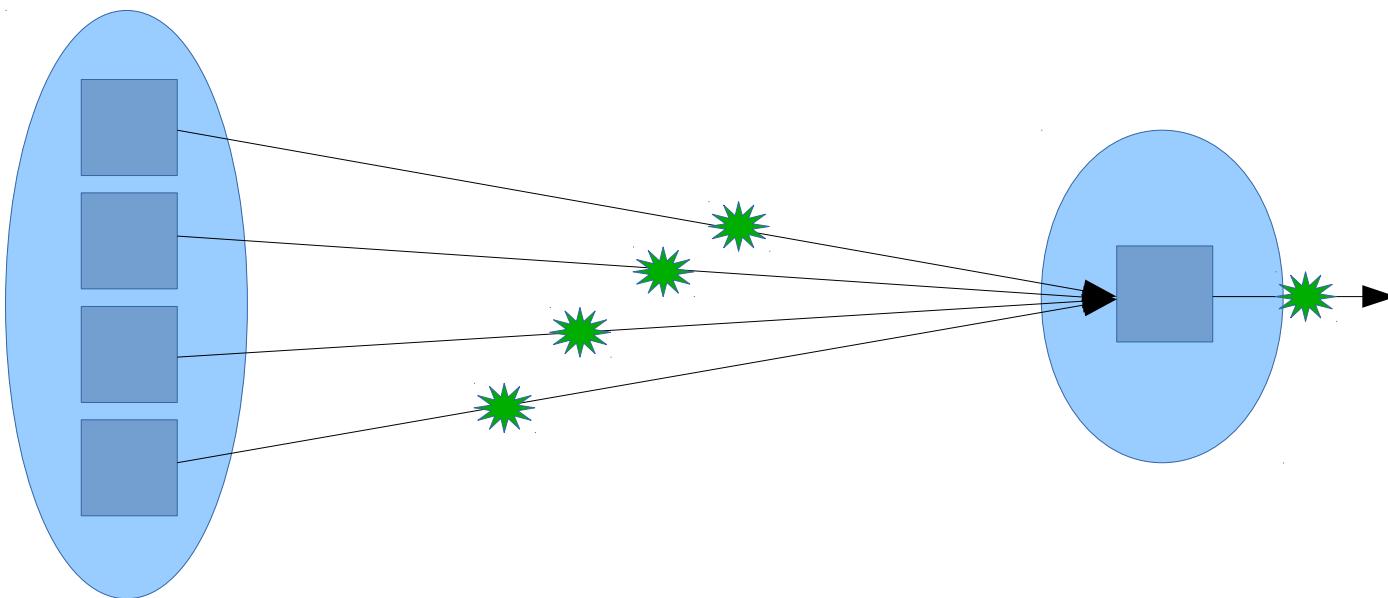
```
weight_rule = AdditiveWeightDependence(  
    w_min=0.0, w_max=2, A_plus=0.5, A_minus=0.5)
```

```
stdp_model = STDPMechanism(  
    timing_dependence = time_rule,  
    weight_dependence = weight_rule)
```

```
syn_dyn = SynapseDynamics(slow = stdp_model)
```

```
Projection(pop_src, pop_dst, p.AllToAllConnector(weights,  
delays), syn_dyn)
```

Example



Synapses with long-term plasticity

Building the network – 1

```
import pyNN.spiNNaker as p
import numpy

p.setup(timestep=1.0, min_delay =
1.0, max_delay = 16.0)

end_time = 1100

cell_params_lif = {
    'cm' : 0.25, # nF
    'i_offset' : 0.0,
    'tau_m' : 20.0,
    'tau_refrac': 2.0,
    'tau_syn_E' : 5.0,
    'tau_syn_I' : 5.0,
    'v_reset' : -70.0,
    'v_rest' : -65.0,
    'v_thresh' : -50.0
}

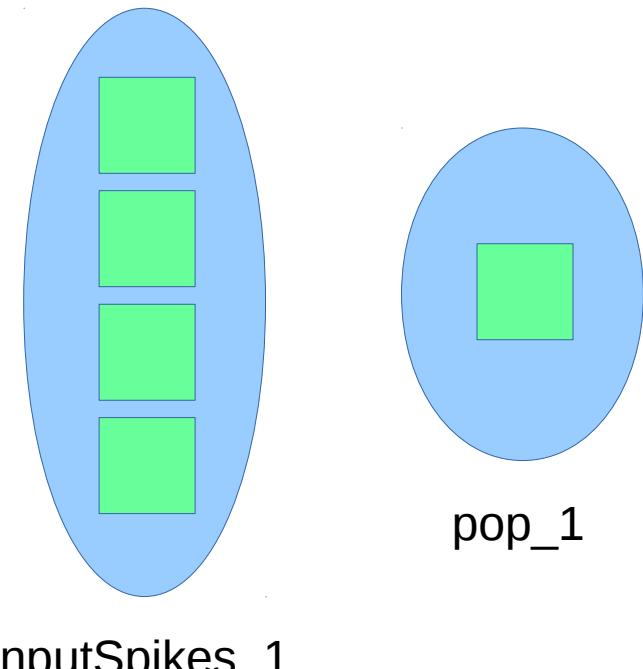
SpikeArray = {
    'spike_times':
    [range(0,end_time,50),
     range(3,end_time,50),
     range(6,end_time,50),
     range(9,end_time,50)]}

populations = list()
projections = list()
```

Building the network – 2

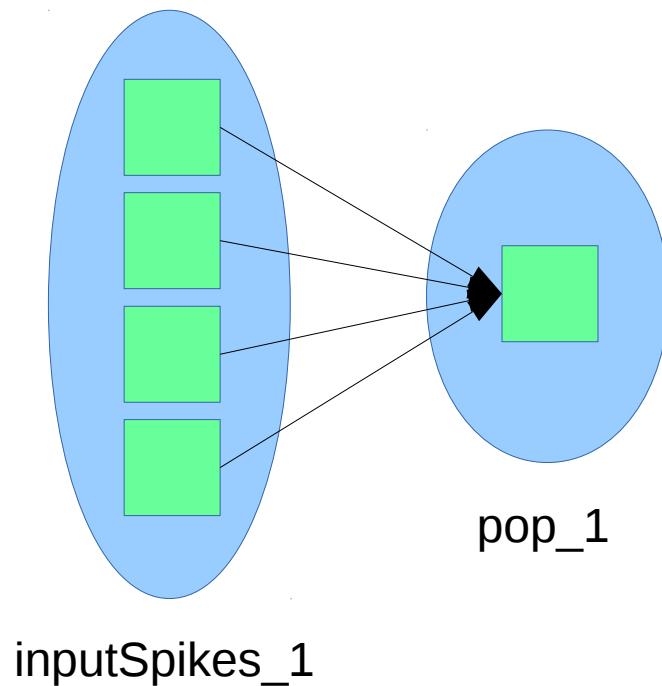
```
p.Population(  
    4,  
    p.SpikeSourceArray,  
    spikeArray,  
    label='inputSpikes_1')
```

```
p.Population(  
    1,  
    p.IF_curr_exp,  
    cell_params_lif,  
    label='pop_1')
```



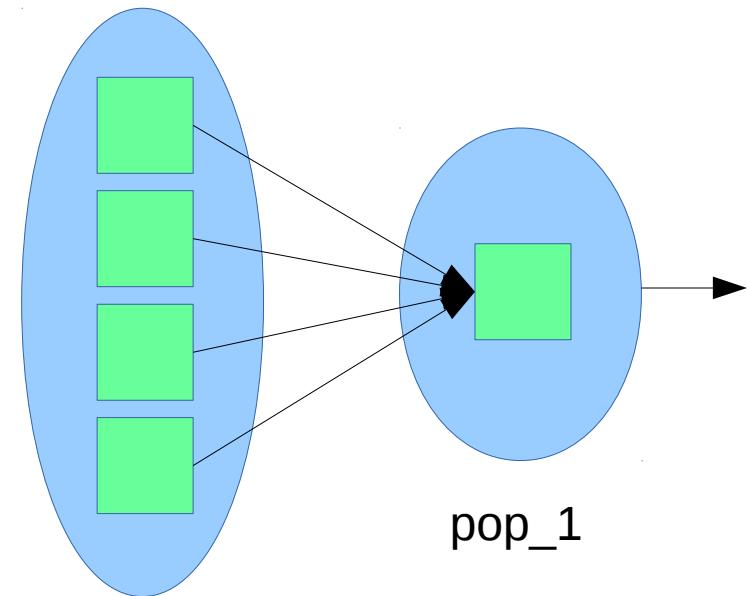
Building the network - 3

```
t_rule = p.SpikePairRule(  
    tau_plus=1, tau_minus=1,  
    nearest=True)  
w_rule = p.AdditiveWeightDependence(  
    w_min=0.0, w_max=2,  
    A_plus=0.5, A_minus=0.5)  
  
stdp_model = p.STDPMechanism(  
    timing_dependence = t_rule,  
    weight_dependence = w_rule,  
)  
  
p.Projection(  
    populations[0],  
    populations[1],  
    p.AllToAllConnector(  
        weights = weight_to_spike,  
        delays = delay),  
    synapse_dynamics =  
        p.SynapseDynamics(  
            slow = stdp_model)))
```

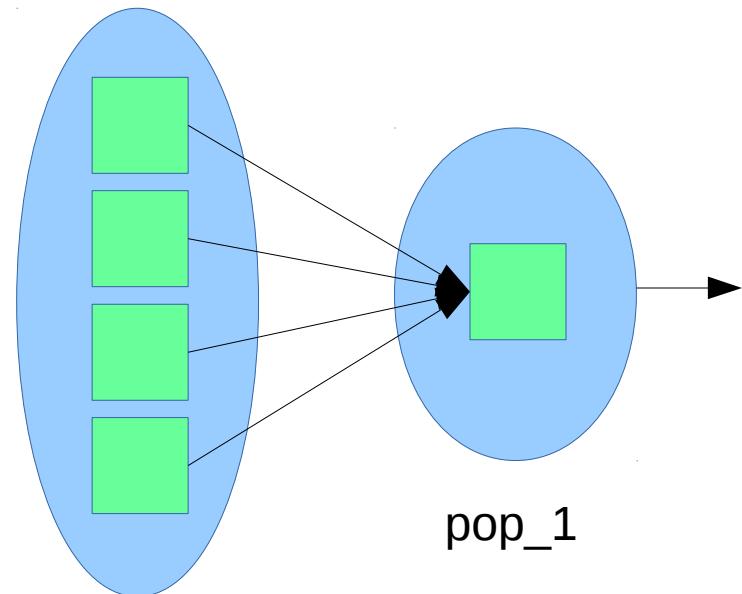
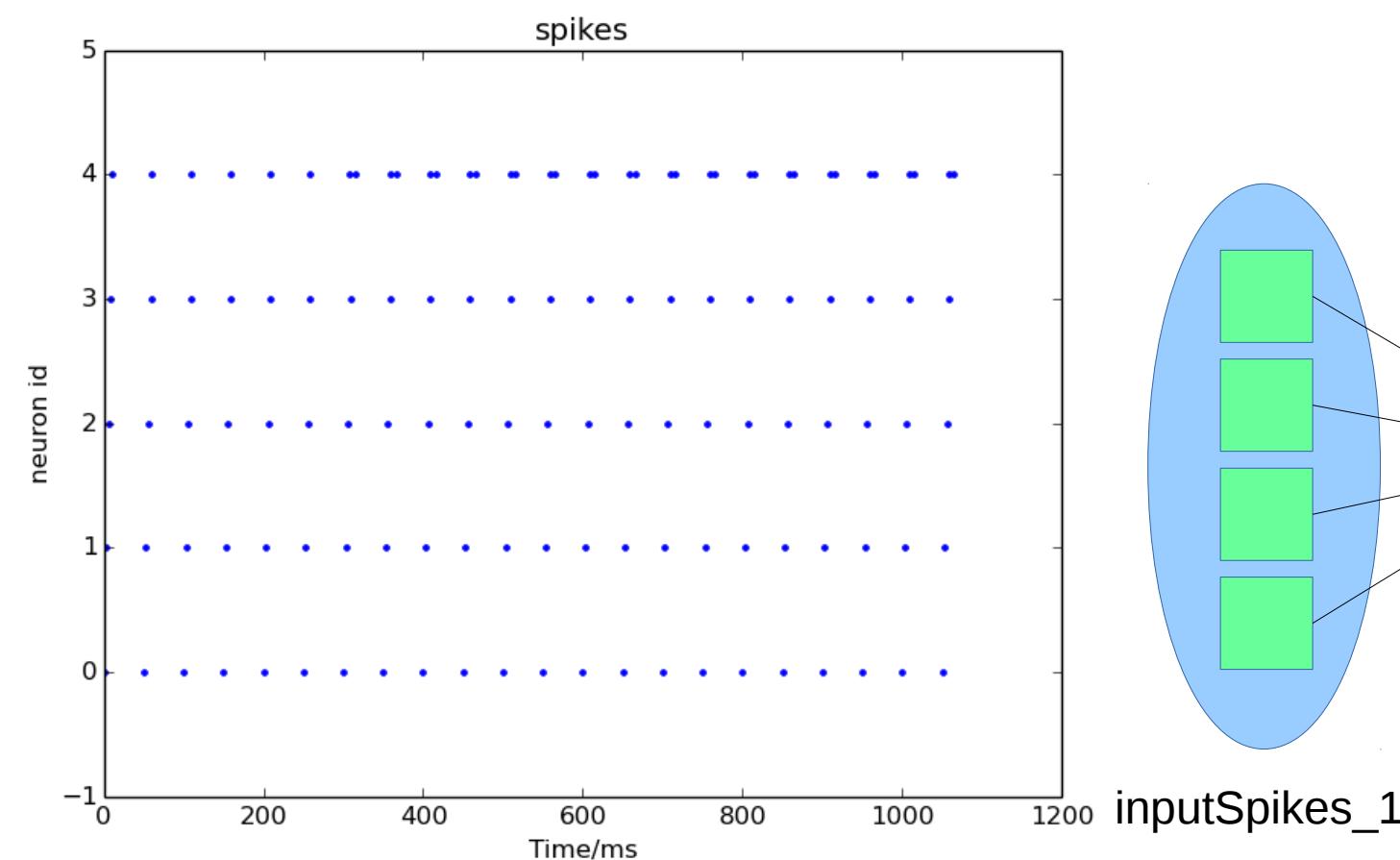


Running the network

```
populations[1].record()  
  
p.run(end_time)  
  
spikes_2 = populations[1].getSpikes()
```



Results – 1



Results – 2

Evolution of the synaptic weights:

